

Servo Catalog

Devotes in Better Product Experience and Support Customers Success.

**Better Team,
Better Products,
Contribute to Intelligent Manufacturing.**



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2021 Edition

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Servo Drive

VD1 Servo and Motor Product Line-up

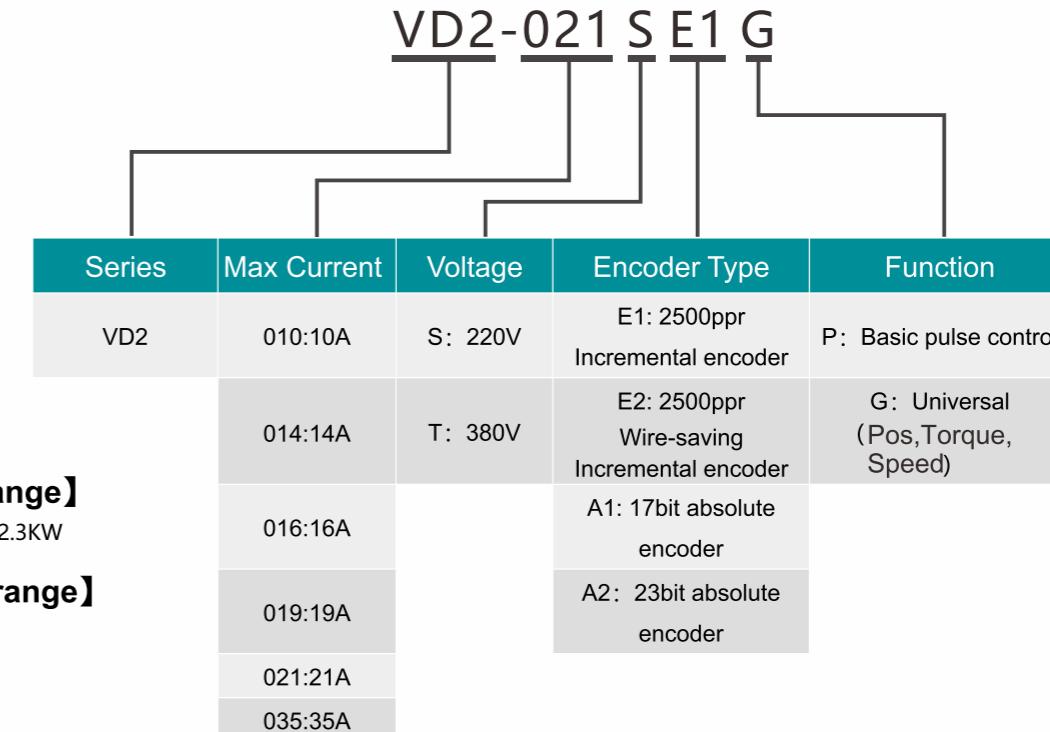
Voltage Class	Servo Drive			Motor				Remarks
	Power (KW)	Model	Drive Type	Frame Size	Model	Rated Speed (rpm)	Rated Torque (N.m)	
220V	0.4	VD1-040SE1G	Type A	60	WD60M-04030S-E1B	3000	1.27	Brake not supported in VD1 Servo
				80	WD80M-04030S-E1B	3000	1.27	
		VD1-040SE1G5		60	WD60M-04030S-E1F	3000	1.27	
	0.75	VD1-075SE1G	Type A	80	WD80M-07530S-E1B	3000	2.39	
		VD1-075SE1G5		80	WD80M-07530S-E1F	3000	2.39	
		VD1-075SE1G-20S		80	WD80M-07520S-E1B	2000	3.5	

Vd2 Servo and Motor Product Line-up

Voltage Class	Servo Drive			Motor					
	Power (KW)	Model	Drive Type	Frame Size	Model	Rated Speed (rpm)	Rated Torque (N.m)	Brake	
220V	0.4	VD2-010SA1G	Type A	60	WD60M-04030S-A1F	3000	1.27	-	
				60	WD60M-04030S-A1G	3000	1.27	Brake	
	0.75	VD2-014SA1G		80	WD80M-07530S-A1F	3000	2.39	-	
				80	WD80M-07530S-A1G	3000	2.39	Brake	
	1.0	VD2-016SE1G-E083	Type B	80	WD80M-10025S-E1B	2500	4	-	
				80	WD80M-10025S-E1C	2500	4	Brake	
		VD2-016SE1G-E092	Type B	130	WD130M-10025S-E1B	2500	4	-	
				130	WD130M-10025S-E1C	2500	4	Brake	
	1.1	VD2-016SE1G-E101	Type B	80	WD80M-11030S-E1B	3000	3.5	-	
				80	WD80M-11030S-E1C	3000	3.5	Brake	
		VD2-019SE1G-E113	Type B	130	WD130M-15025S-E1B	2500	6	-	
				130	WD130M-15025S-E1C	2500	6	Brake	
	1.5	VD2-016SE1G-E122	Type B	130	WD130M-15015S-E1B	1500	10	-	
				130	WD130M-15015S-E1C	1500	10	Brake	
		VD2-019SE1G-E132	Type B	110	WD110M-18030S-E1B	3000	6	-	
				110	WD110M-18030S-E1C	3000	6	Brake	
	1.8	VD2-019SE1G-E151	Type B	130	WD130M-20025S-E1B	2500	7.7	-	
	2.0	VD2-021SE1G-E161	Type B	130	WD130M-23015S-E1B	1500	15	-	

Remarks: The above models are equipped with power cables and encoder cables as standard.
The default cable length is 3 meters, and optional lengths: 5 meters and 10 meters.

Naming Rules

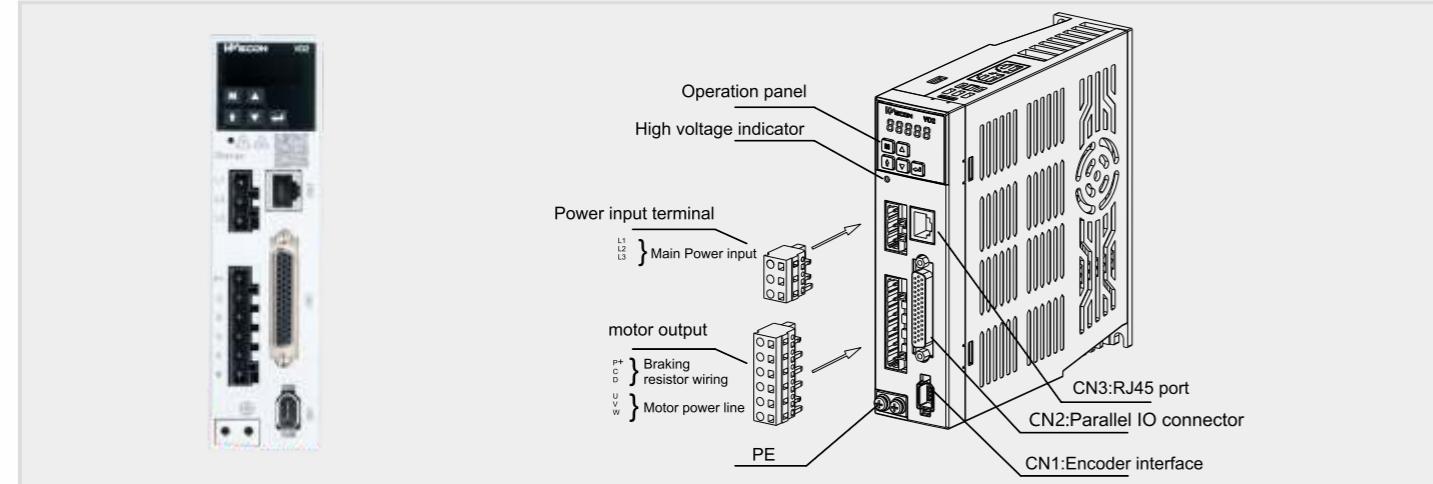


Servo Motor and Cable Matching Table

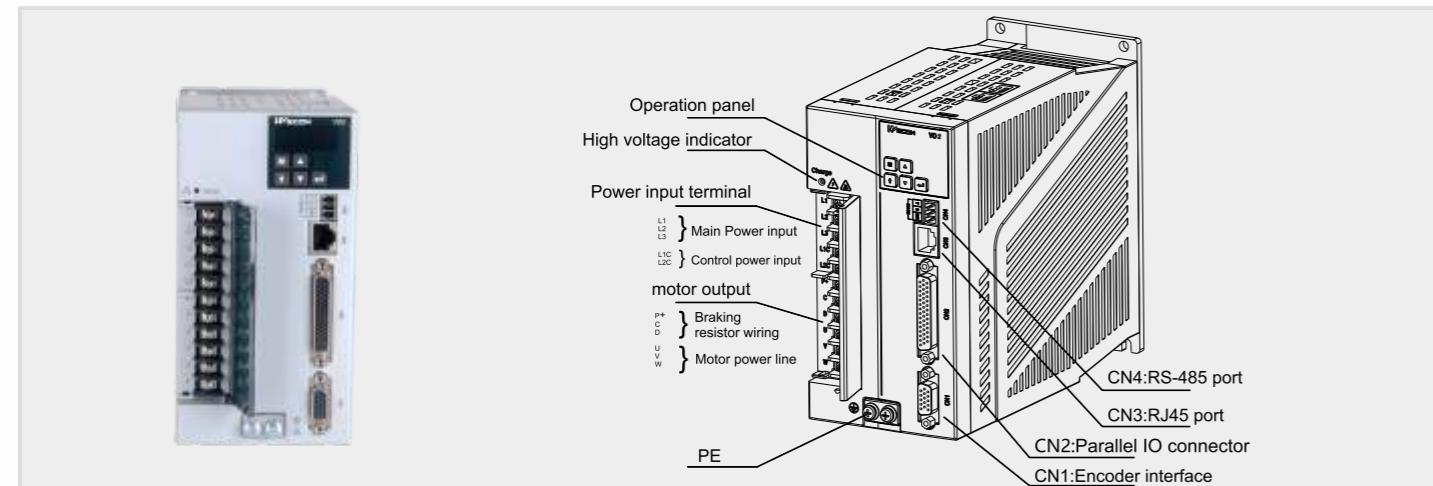
Series	Motor Model	Cable Type	Cable Model
VD1 Series	WD60M-04030S-Exx	Power Cable	P-L4G-R4M-x-xx
	WD80M-07530S-Exx	Encoder Cable	E-M20G-R15M-x-xx
	WD80M-07520S-Exx		
VD2 Series	WD60M-04030S-Axx	Power Cable	P-Z3O1-R4M-x-xx
	WD80M-07530S-Axx	Encoder Cable	E-J1394-R9M-x-xx
	WD80M-11030S-Exx	Power Cable	P-U3O1-R4M-x-xx
	WD80M-10025S-Exx	Encoder Cable	E-D15G-R15M-x-xx
	WD110M-18030S-Exx	Power Cable	P-U3O1-H28J4M-x-xx
VD2 Series	WD130M-10025S-Exx	Power Cable	
	WD130M-15025S-Exx	Encoder Cable	
	WD110M-18030S-Exx		
	WD130M-15015S-Exx		
	WD130M-20025S-Exx	Encoder Cable	E-D15G-H28J15M-x-xx

Servo Drive Interface

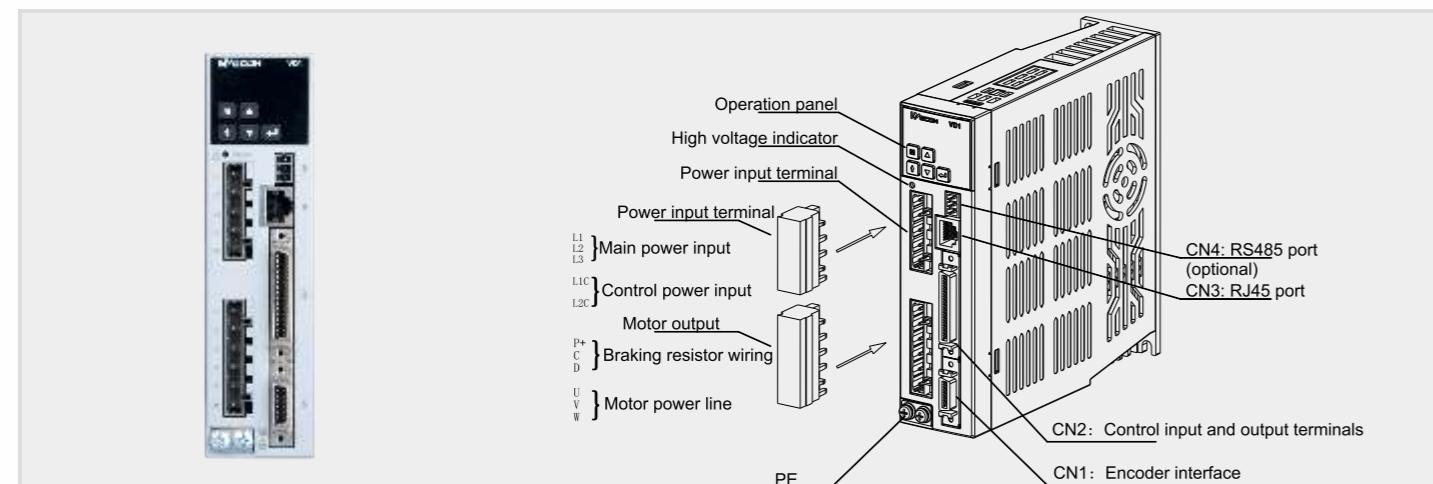
■ VD2 Type A Servo Drive Interface



■ VD2 Type B Servo Drive Interface

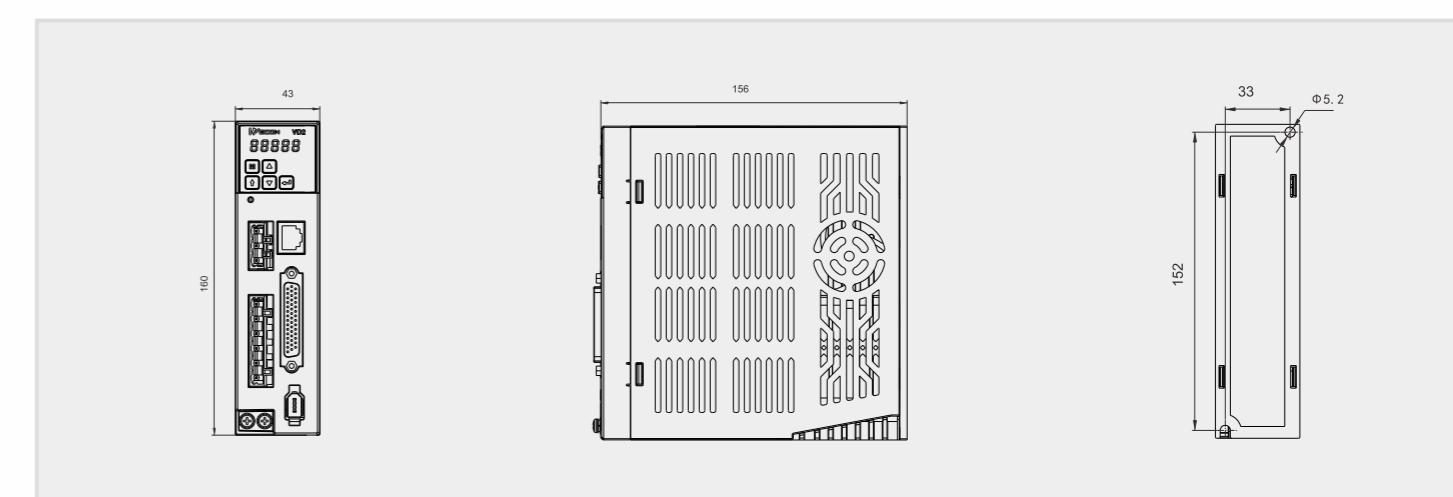


■ VD1 Servo Drive Interface

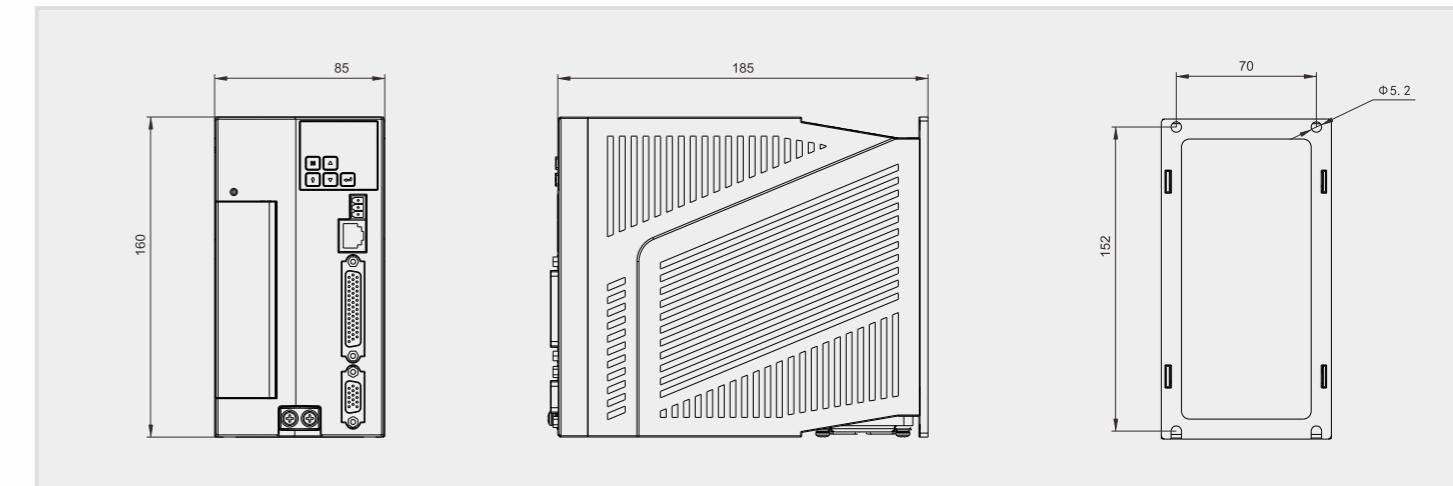


Servo Drive Dimension

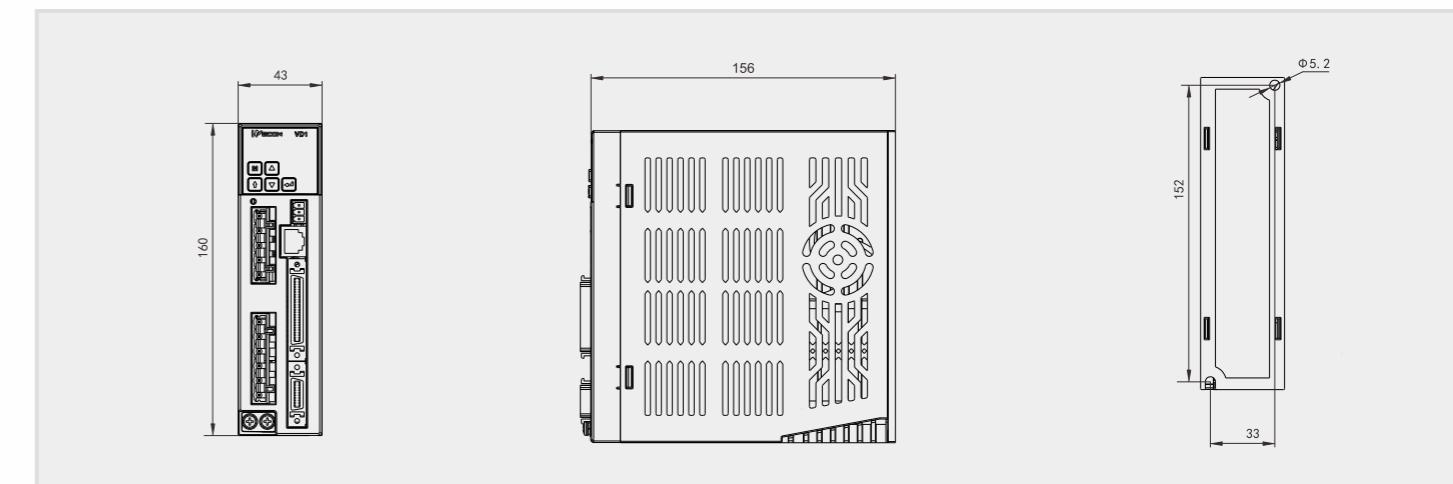
■ VD2 Type A Dimension



■ VD2 Type B Dimension



■ VD1 Dimension

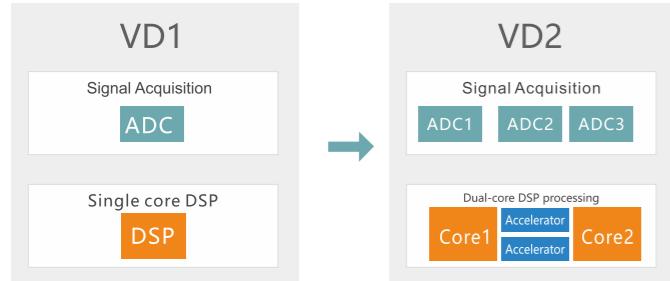


VD2 Servo Drive

Features

- High Response

Using dual-core DSP+FPGA processing, the response speed is 4 times higher than that of the VD1 series.

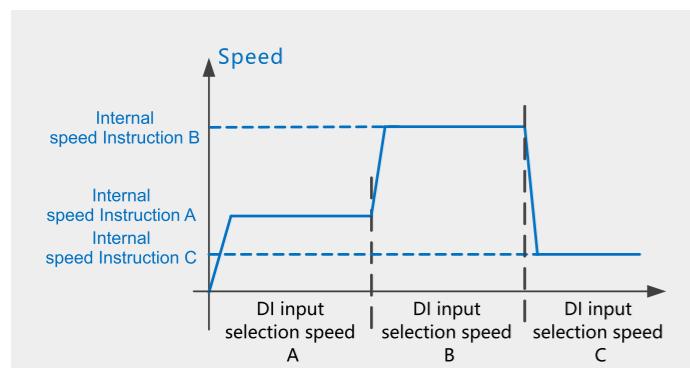


- Strong Protection

Coating protection, anti-corrosion damage. Rich protection function, more stable.



- Support internal multi-speed instruction



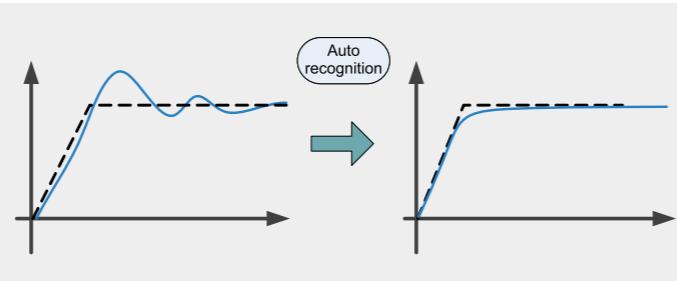
- Support instantaneous load rate and average load rate monitoring

- Convenient on-site debugging-playback of fault record panel

- Support brake output control

- Easy to Debug

Automatic load parameter tuning function

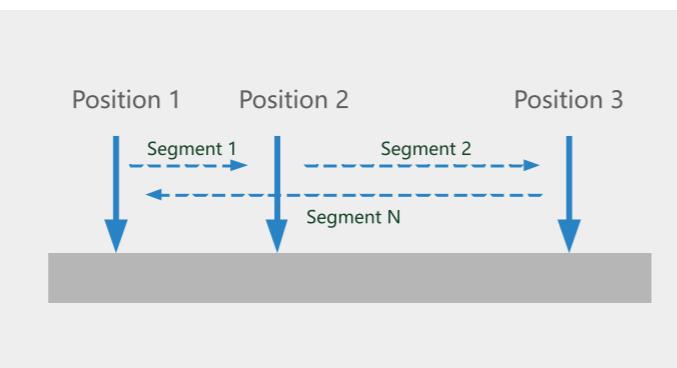


- Personalise

Virtual DI/DO function, four-channel real-time oscilloscope.



- Support internal multi-segment position instruction



- Support real-time automatic load inertia recognition

- Support pulse frequency monitoring

■ VD2 Servo Drive Parameter

	Item	Content
Basic Specifications	Control Method	IGBT PWM controlled sine wave current drive
	Encoder	2500ppr incremental encoder, 17 bit absolute encoder
	Input Signal	8*DI, Select input function according to function code configuration
	Output Signal	4*DO, Select output function according to function code configuration
	Analog Signal Input	2 channel AI input, range(-10v~10v)
	Pulse Signal Input	Open collector or differential input
	Pulse Feedback Output	A,B,Z differential output
	Internal Instructions	Support 8 internal speed commands and multiple internal position commands
	Communication	Modbus Communication
	PC	RS422 port, Parameter setting, monitoring status, waveform viewing, parameter auto-tuning, via computer channel 1
General Function	Braking Resistor	Built-in braking resistor, supporting external braking resistor
	Automatic Parameter Tuning	It can cooperate with the host computer for automatic load inertia identification and automatic rigidity level, and the parameters self-tuning.
	Waveform Viewing	View position, speed, torque and other curves on PC in real time
	Waveform Storage	The waveform sampling frequency is 1KHz, and the original waveform data can be stored for up to 10s
	Parameter Import/export	Support batch parameter import and export; support PLC automatic configuration of servo parameters (supported by some models)
	Vibration Suppression	Suppress mechanical vibration by setting vibration suppression parameters
	Protective Function	Overvoltage, undervoltage, overcurrent, overspeed, overload, overheating, encoder failure, excessive position deviation, torque limit, speed limit, etc.
	Brake	Support brake output control
	Universal Control DI	Servo enable (SON), fault and warning clear (A-CLR), forward drive prohibition (POT), reverse drive prohibition (NOT), command reverse (C-SIGN), emergency stop (E-STOP), Gain switching (GAIN-SEL), Multi-stage internal speed command selection(INSPD1, INSPD2, INSPD3)
	Universal Control DO	Servo ready (RDY), fault signal (ALM), warning signal (WARN), rotation detection (TGON), zero speed signal (ZSP), torque limit (T-LIMIT), speed limit (V-LIMIT), servo on state output (SRV-ST), servo brake output (BRK-OFF)
Function Setting	Input Control	Deviation counter clear (CL), electronic gear switching 1 (GEAR-SEL), pulse input inhibit (INH), command inversion (C-SIGN)
	Output Control	Positioning complete (P-COIN), positioning approach (P-NEAR)
	Pulse Frequency	max. 500khz
	Pulse Type	Pulse + Direction, CCW/CW pulse, Orthogonal coding
	Electronic Gear Ratio	Range: 0.01 ~ 100
	Pulse Filtering	Low-pass filter or smooth filter
	Pulse Output	Differential orthogonal coding A, B, Z output, PPR is settable, can be set to integer or fraction.
	Torque Limit	Forward / reverse operation torque limit is settable
	Speed Limit	Forward / reverse operation speed limit is settable
	Control Input	Zero clamp (ZCLAMP), command inversion (C-SIGN), Speed limit analog input
Speed Mode	Control Output	Velocity consistent (V-COIN), Speed approach (V-NEAR)
	Analog Input	-10V~+10V analog input
	Internal Command	Set the speed via internal function code
	Soft Start	acc. and dec. time are settable
	Zero Clamp	Motor speed can be clamped to zero via the setting of zero clamp function
Torque Mode	Torque Limit	Set the torque limit
	Command Output	Command inversion (C-SIGN), Speed limit analog input
	Control Output	Torque reached (T-COIN), speed limit (V-LIMIT)
	Analog Input	-10V~+10V analog input
	Internal Command	Set torque through internal parameter
Speed Limit	Speed Limit	Limits maximum speed in torque mode

■ VD1 Servo Drive Parameter

Item		Content	
Basic specifications	control method	IGBT PWM controlled sine wave current drive	
	encoder	2500ppr incremental encoder	
	Input signal	8*DI, Select input function according to function code configuration	
	Output signal	4*DO, Select output function according to function code configuration	
	Analog signal input	2 channel AI input, range(-10v~10v)	
	Pulse signal input	Open collector or differential input	
	Pulse feedback output	A,B,Z differential output	
	Modbus comm	channel 1	
	communication	RS422 port, Parameter setting, monitoring status, waveform viewing, parameter auto-tuning, via computer	
	pc		
General function	Braking resistor	Built-in braking resistor, supporting external braking resistor	
	Automatic parameter tuning	It can cooperate with the host computer for automatic load inertia identification and automatic rigidity level, and the parameters self-tuning.	
	Waveform viewing	View position, speed, torque and other curves on PC in real time	
	Vibration suppression	Suppress mechanical vibration by setting vibration suppression parameters	
	Protective function	Overvoltage, undervoltage, overcurrent, overspeed, overload, overheating, encoder failure, excessive position deviation, torque limit, speed limit, etc.	
	Universal control DI	Servo enable (SON), fault and warning clear (A-CLR), forward drive prohibition (POT), reverse drive prohibition (NOT), command reverse (C-SIGN), emergency stop (E-STOP), Gain switching (GAIN-SEL)	
	Universal control DO	Servo ready (RDY), fault signal (ALM), warning signal (WARN), rotation detection (TGON), zero speed signal (ZSP), torque limit (T-LIMIT), speed limit (V-LIMIT), servo on state output (SRV-ST)	
	Input control	Deviation counter clear (CL), electronic gear switching 1 (GEAR-SEL), pulse input inhibit (INH), command inversion (C-SIGN)	
	Output control	Positioning complete (P-COIN) , positioning approach (P-NEAR)	
	Pulse frequency	max. 500khz	
Function setting	Pulse type	Pulse + Direction, CCW/CW pulse, Orthogonal coding	
	input	Electronic gear ratio	Range: 0.01 ~ 100
		Pulse filtering	low-pass filter or smooth filter
		Pulse output	Differential orthogonal coding A, B, Z output, PPR is settable
		Torque limit	Forward / reverse operation torque limit is settable
		Speed limit	Forward / reverse operation speed limit is settable
	Control input	Zero clamp (ZCLAMP) ,command inversion (C-SIGN) ,Speed limit analog input	
	Control output	Velocity consistent (V-COIN) ,Speed approach (V-NEAR)	
	Command input	Analog input -10V~+10V analog input	
	Internal command	set the speed via internal function code	
Speed mode	Soft start	acc. and dec. time are settable	
	Zero clamp	Motor speed can be clamped to zero via the setting of zero clamp function	
	Torque limit	set the torque limit	
	Command output	Command inversion (C-SIGN) , Speed limit analog input	
	Control output	Torque reached (T-COIN) , speed limit (V-LIMIT)	
	Command input	Analog input -10V~+10V analog input	
	Internal command	Set torque through internal parameter	
	Speed limit	Limits maximum speed in torque mode	

Servo Motor

Naming Rules



WD 80 M - 075 30 S - E1 B

WECON Name	Flange Size	Motor Inertia	Rated Power	Rated Speed	Voltage Class	Encoder Type	Motor Structure
WD	40	L: Low inertia	010:100W	15:1500rpm	S:220V	E1:2500ppr Incremental encoder	A: None
	60	M: Medium inertia	020:200W	20:2000rpm	T:380V	E2: 2500ppr Wire-saving Incremental encoder 9-pin interface	B: 4-pole with oil sealing
	80	H: High inertia	040:400W	25:2500rpm		A1: 17bit absolute encoder	C: 4-pole with electromagnetic brake
	90		075:750W	30:3000rpm		A2: 23bit absolute encoder	D: 4-pole with permanent magnetic brake
	100		100:1.0KW				E: None
	110		150:1.5KW				F: 5-pole with oil sealing
	130		180:1.8KW				G: 5-pole with electromagnetic brake
			200:2.0KW				H: 5-pole with permanent magnetic brake
			230:2.3KW				

Definition of Wiring

Motor socket		Motor phase		U		V		W		PE						
		Number		1		2		3		4						
Incremental encoder wiring	Signal	5V	GND	A+	Z-	U+	Z+	U-	B+	V+	W+	V-	B-	A-	W-	PE
	Number	2	3	4	5	6	7	8	9	10	11	12	13	14	15	1

■ VD1 Motor Parameters

Model	Rated Power (kW)	Rated Current (A)	Rated Torque (N·m)	Max. Torque (N·m)	Rated Speed (r/min)	Rotor Inertia (Kg·m ²)	Without Brake Dimension (L/mm)
WD60M-04030S-E1F	0.4	2.1	1.27	4.46	3000	0.61×10^{-4}	115
WD60M-04030S-E1B	0.4	2.6	1.27	3.81	3000	0.407×10^{-4}	133
WD80M-04030S-E1B	0.4	2	1.27	3.8	3000	1.05×10^{-4}	124
WD80M-07530S-E1F	0.75	4	2.39	8.36	3000	1.71×10^{-4}	132
WD80M-07530S-E1B	0.75	3	2.39	7.1	3000	1.82×10^{-4}	151
WD80M-07520S-E1B	0.75	3	3.5	10.5	2000	2.63×10^{-4}	179

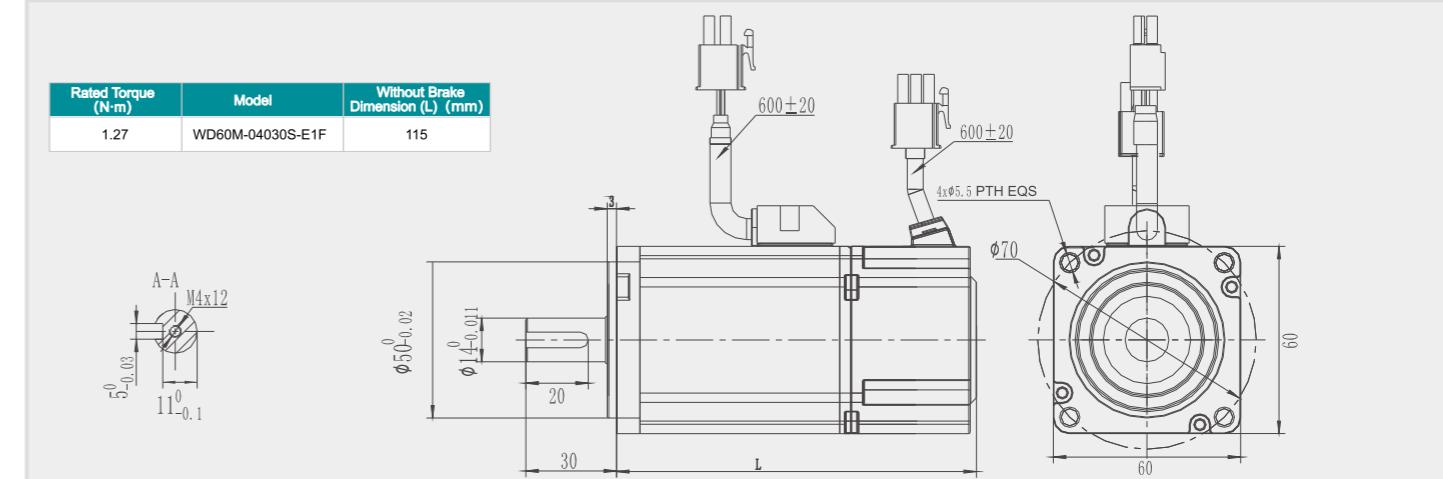
■ VD2 Motor Parameters

Model	Rated Power (kW)	Rated Current (A)	Rated Torque (N·m)	Max. Torque (N·m)	Rated Speed (r/min)	Rotor Inertia (Kg·m²)	Without Brake Dimension (L/mm)	With Brake Dimension (L/mm)
WD60M-04030S-A1F	0.4	2.5	1.27	3.81	3000	0.52×10^{-4}	92	-
WD60M-04030S-A1G		2.5	1.27	3.81	3000	0.62×10^{-4}	-	121.5
WD80M-07530S-A1F	0.75	4.4	2.39	7.17	3000	1.48×10^{-4}	98.5	-
WD80M-07530S-A1G		4.4	2.39	7.17	3000	1.78×10^{-4}	-	132.5
WD80M-10025S-E1B	1.0	4.4	4	12	2500	2.97×10^{-4}	191	-
WD80M-10025S-E1C		4.4	4	12	2500	2.97×10^{-4}	-	231
WD130M-10025S-E1B		4	4	12	2500	8.5×10^{-4}	166	-
WD130M-10025S-E1C		4	4	12	2500	8.5×10^{-4}	-	223
WD80M-11030S-E1B	1.1	4.5	3.5	10.5	3000	2.63×10^{-4}	179	-
WD80M-11030S-E1C		4.5	3.5	10.5	3000	2.63×10^{-4}	-	221
WD130M-15025S-E1B	1.5	6	6	18	2500	12.6×10^{-4}	179	-
WD130M-15025S-E1C		6	6	18	2500	12.6×10^{-4}	-	236
WD130M-15015S-E1B		6	10	25	1500	19.4×10^{-4}	213	-
WD130M-15015S-E1C		6	10	25	1500	19.4×10^{-4}	-	294
WD110M-18030S-E1B	1.8	6.0	6	18	3000	7.6×10^{-4}	219	-
WD110M-18030S-E1C		6.0	6	18	3000	7.6×10^{-4}	-	293
WD130M-20025S-E1B	2.0	7.5	7.7	22	2500	15.3×10^{-4}	192	-
WD130M-23015S-E1B	2.3	9.5	15	30	1500	27.7×10^{-4}	241	-

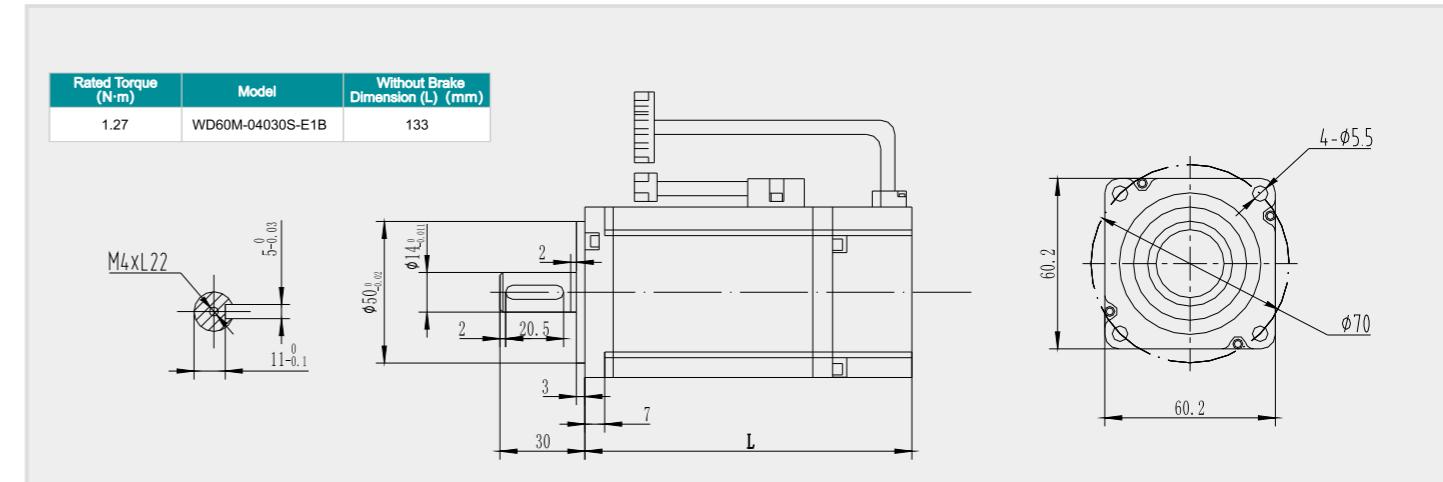
VD1 Motor Dimension

■ 60 Series Motor Dimension

Rated Torque (N·m)	Model	Without Brake Dimension (L) (mm)
1.27	WD60M-04030S-E1F	115

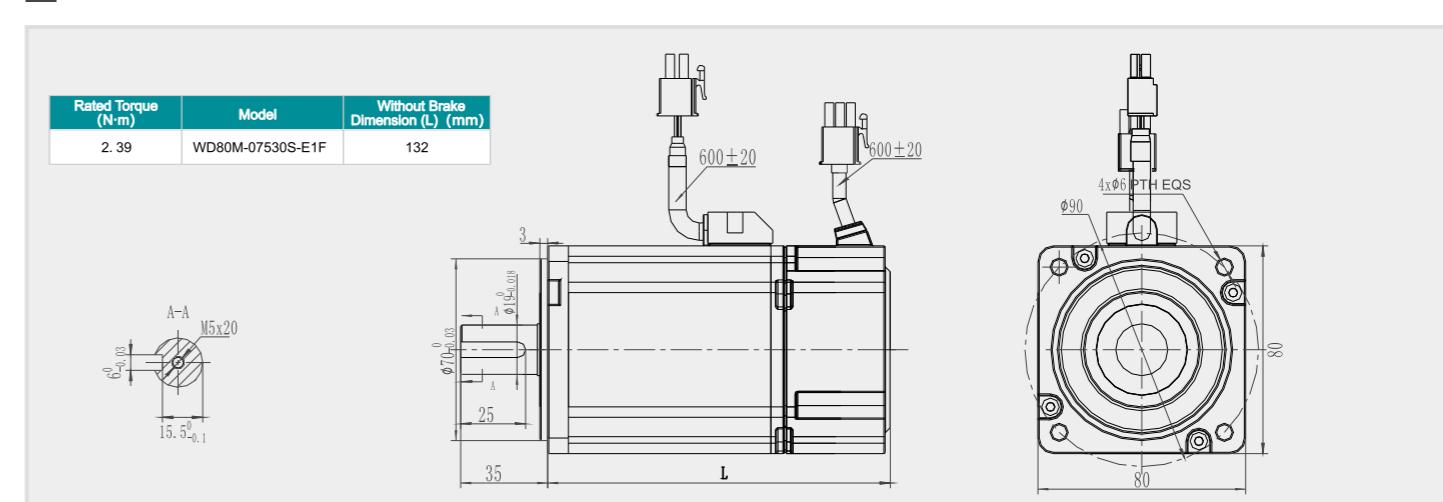


Rated Torque (N·m)	Model	Without Brake Dimension (L) (mm)
1.27	WD60M-04030S-E1B	133



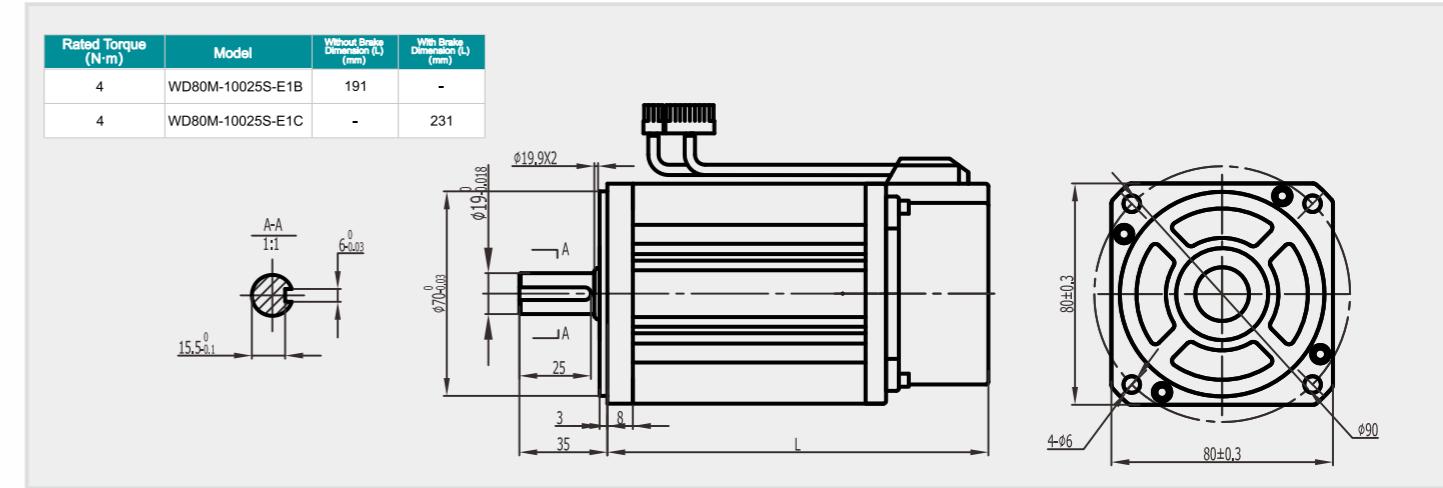
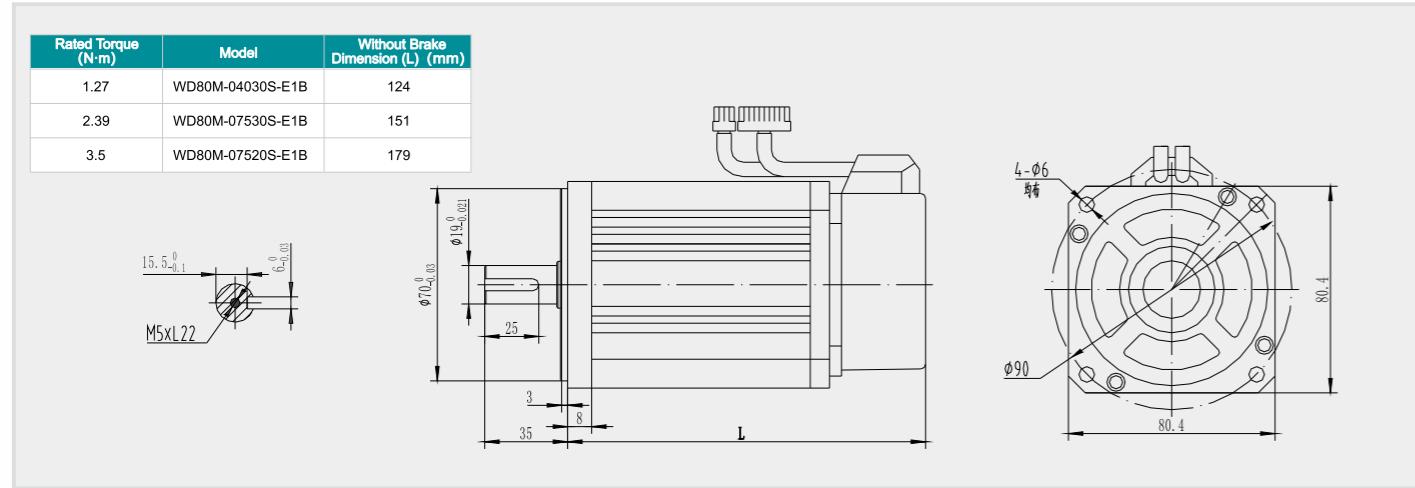
■ 80 Series Motor Dimension

Rated Torque (N·m)	Model	Without Brake Dimension (L) (mm)
5.00	WTG3000 Series	105



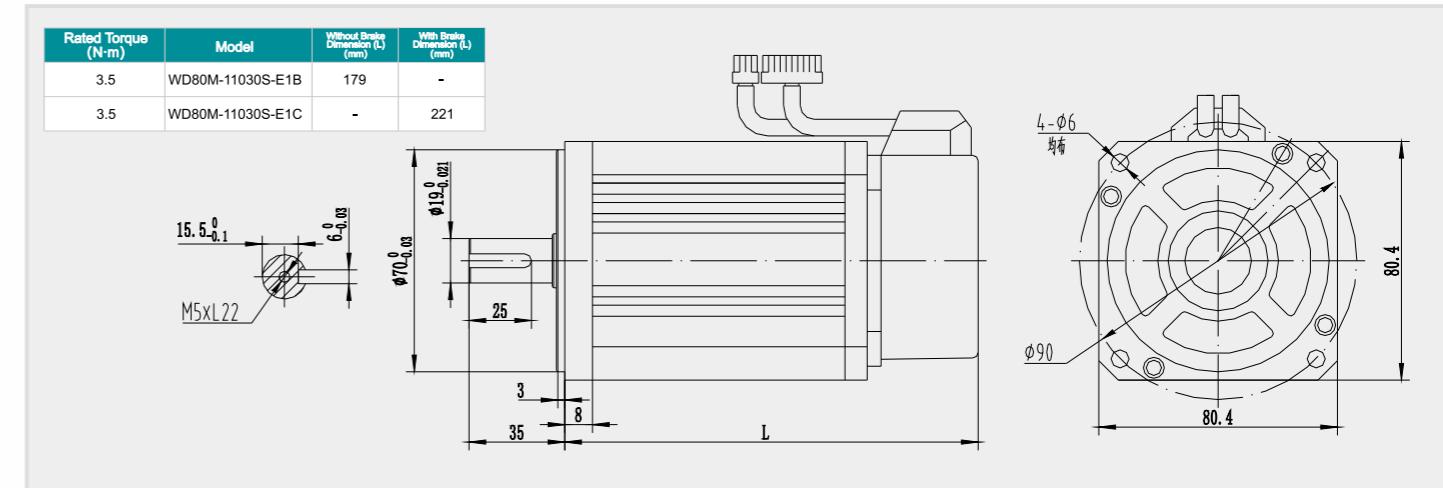
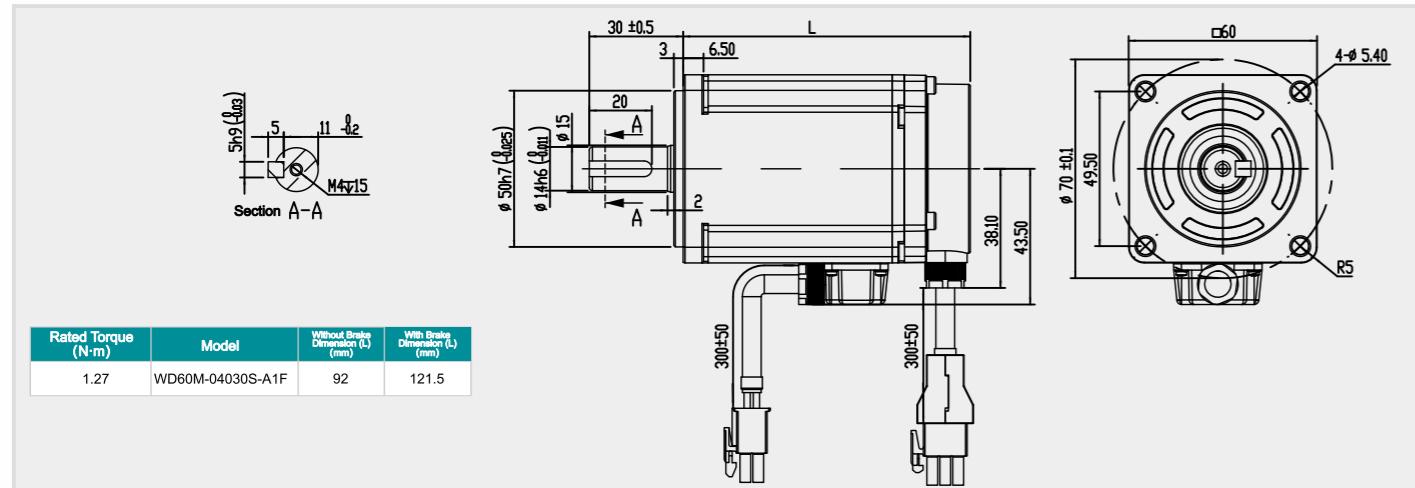
Unit: mm

Unit: mm

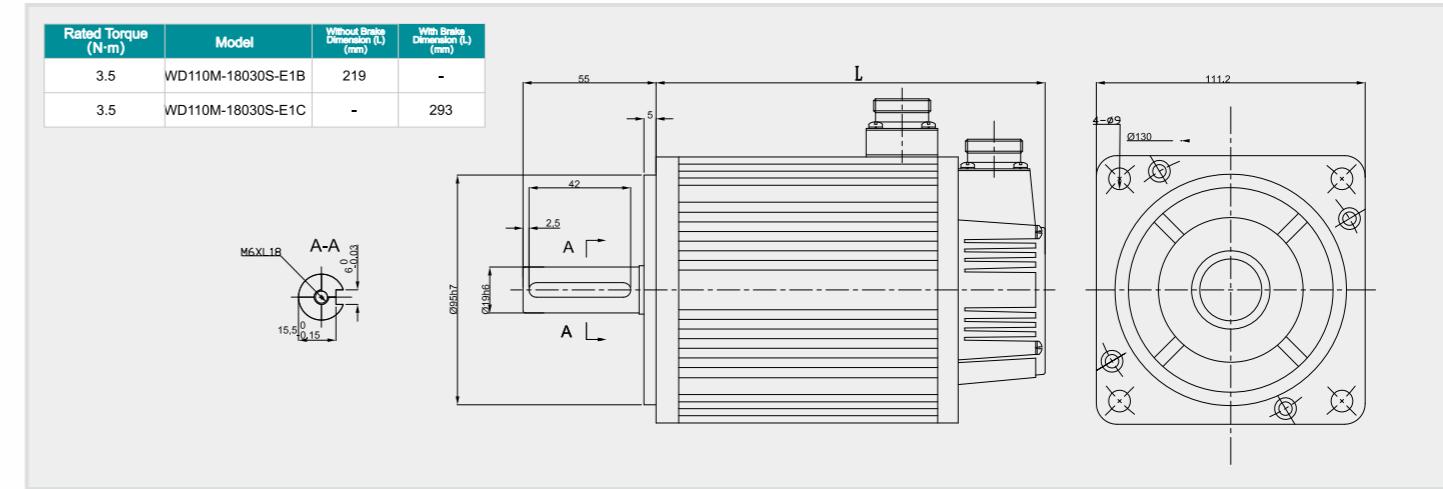
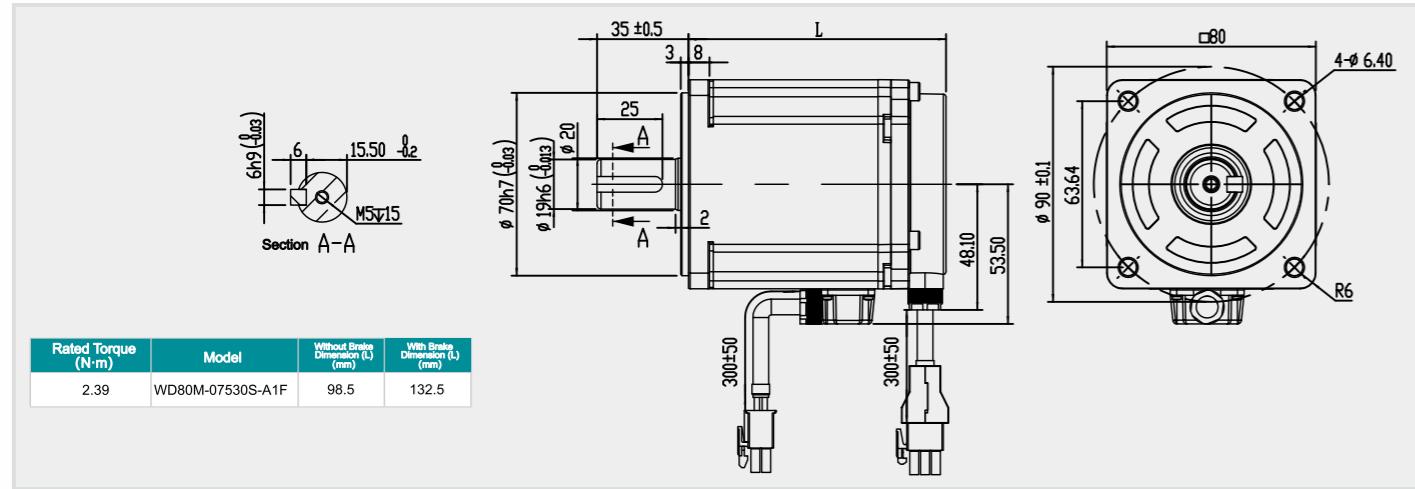


VD2 Motor Dimension

■ 60 Series Motor Dimension



■ 80 Series Motor Dimension



Unit: mm

■ 130 Series Motor Dimension

